



GPS: Theory, Algorithms and Applications

Guochang Xu

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This, the second edition of the hugely practical reference and handbook describes kinematic, static and dynamic Global Positioning System theory and applications. It is primarily based upon source-code descriptions of the KSGSoft program developed by the author and his colleagues and used in the AGMASCO project of the EU. This is the first book to report the unified GPS data processing method and algorithm that uses equations for selectively eliminated equivalent observations.

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